## C-NAV2050



# C-NAV DGPS

The C-Nav2050 sensor consists of a 10-channel dual-frequency precision GPS receiver, two additional channels for receiving Satellite Based Augmentation System (SBAS) signals and an L-Band demodulator for reception of C-Nav correction service. The sensor can output raw data as fast as 50Hz and Position Velocity Time (PVT) data as fast as 25Hz through two 115kbps serial ports.



### THE C-NAV2050 FAMILY OF RECEIVERS:

- The C-Nav2050G provides 64MB internal memory for data storage and provides the user with up to 5Hz measurement and position solutions. In addition, optional 10Kz and 25Hz Fast Positioning Update rates are available as well as raw data measurement outputs at 10Hz, 25Hz or 50Hz.
- The C-Nav2050M has all the standard features of the C-Nav2050G plus a 1PPS output port and a combined Event/CAN Bus interface port. In addition, 25Hz Fast Position Update rate is available and optional raw data measurement outputs up to 50Hz, and optional RTK Position Velocity and Time (PVT) solution at up to 5Hz are available.
- The C-Nav2050R has all the standard features of the C-Nav2050G but provides for two L-Band signal connections, one for the Dual Frequency GPS antenna and the second for a hi-gain L-Band communication satellite antenna.

The C-Nav2050 GPS family of receivers provides survey positioning services on a global basis.

S	FEATURES		PERFORMANCE		
•••	• "All-in-view" tracking		GPS RECEIVER PERFORMANCE		
U	<ul> <li>Global decimeter-level accuracy using RTG corrections</li> </ul>		<ul> <li>Real-time Kinematic Accuracy (RTK Option Only)</li> </ul>		
-	<ul> <li>Fully automatic acquisition of satellite broadcast corrections</li> </ul>			Centimeter level	
ш	<ul> <li>Configurable for global L-band satellite coverage – RTG, WAAS, EGNOS</li> </ul>		Real-time StarFire DGPS Accuracy		
		ight package for mobile applications	Position (H):	<10 cm	
Δ_		S correction input in NCT, RTCM v2.2 or CMR format	Position (V):	<30 cm	
	○ L1 & L2 full wavelen		Velocity:	0.01 m/s	
S	<ul> <li>C/A, P1 &amp; P2 code tracking</li> </ul>		<ul> <li>Pseudo-range Measurement Precision (RMS)</li> </ul>		
•••	<ul> <li>User programmable</li> </ul>		Raw C/A code:	20cm @ 42 dB-Hz	
	<ul> <li>Minimal data latence</li> </ul>		Raw carrier		
	○ 2 separate SBAS (W)		Phase noise:	L1: 0.95 mm @ 42 dB-Hz	
I	<ul> <li>Superior interference</li> </ul>			L2: 0.85 mm @ 42 dB-Hz	
	<ul> <li>Patented multipath</li> </ul>	11	• User Programmable	Output Rates	
U	Supports NMEA 0183		PVT:	, 25Hz, 10Hz, 5 Hz, 2Hz, 1Hz, or slower	
	<ul> <li>Self-survey mode (p</li> </ul>		Raw data:	50Hz, 25Hz, 10Hz, 5Hz, 2Hz, 1Hz, or slower	
	• CAN bus interface (C-Nav2050M only)		Data Latency		
	IPPS Output (C-Navi		PVT:	< 20 ms at all nav rates	
	• Event Marker (C-Nav	(2050M only)	Raw data:	< 20 ms at all rates	
-	, , , , , , , , , , , , , , , , , , ,	5,	• Time-to-first-fix		
	PHYSICAL/E	NVIRONMENTAL	Cold Start, Satelli	te	
	Size (L x W x H):	8.18" x 5.67" x 3.06" (20.8 x 14.4 x 7.8 cm)	Acquisition:	< 60 seconds (typical)	
	• Weight:	4 lbs (1.81 kg)	Satellite		
	• External Power		Reacquisition:	< 1 second	
	Input Voltage:	10 VDC to 30 VDC	Opplaying Dynamics		
	Consumption:	<10 W	Acceleration:	up to 6g	
	Connectors		Speed*:	< 300 m/s	
	I/O Ports:	2 x 7 pin Lemo	Altitude*:	< 60,000 ft	
	DC Power:	4 pin Lemo	IPPS Resolution	12.5nS (C-Nav2050M only)	
	RF Connector: TNC (with 5 VDC bias for antenna/LNA)			*Restricted by	

• Temperature (ambient)

Operating: Storage:

• Humidity:

2.5

2

15

1

0.5

0

-0.5

-1

-1.5

-2

-2.5

0:00

3:00

— LAT (meters)

6:00

9:00

-40° C to +55° C

-40° C to +85° C

• Tested in accordance with MIL-STD-810F for: Low pressure, solar

C-Nav Analysis - APS [RTG] Activation Mode

SD: Lat =0.052 Lon =0.054 HAE =0.169

12:00

Time UTC

— LON (meters)

15:00

18:00

21:00

HAE (meters)

0:00

radiation, rain, humidity, salt fog, sand and dust, and vibration

95% non-condensing

\*Restricted by export laws

#### **I/O CONNECTOR ASSIGNMENTS**

**PVT** 

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• Data Interfaces:
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2 serial ports; from 1200 bps to 115.2 kbps CAN Bus I/F (C-Nav2050M only) Event Marker I/P (C-Nav2050M only)

#### COMMUNICATIONS PORT FUNCTIONS

NCT Proprietary:	Data, Control
	Code Corrections
• NMEA Output:	Data

#### **INPUT/OUTPUT DATA MESSAGES** o

NCT Proprietary					
Data:					

Raw Measurement Satellite Messages Nav Quality **Receiver Commands** 

• NMEA Messages (Output):

• Code Corrections:

ALM, GGA, GLL, GSA, GSV, RMC, VTG, ZDA, and GST RTG (proprietary) – Internal LBM WCT (proprietary) - Internal LBM SBAS (WAAS/EGNOS) - Internal GPS DGPS (RTCM Type 1 or 9) – External I/O RTK (RTCM, CMR, NCT)

#### LED DISPLAY FUNCTIONS (DEFAULT)

- Link (Selectable)
- Base Station

• GPS Position Quality

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